

More on Kalman Filtering

Outline

- Helix fitting in 3-D.
- Alternating UV measurements.
- Performance of the KF with a small number of measurements (22).
- Are there any failure modes?
 - Helices generated over a range of the radius of curvature (R).
 - Helices generated over a range of the dip angle (λ).
- Sensitivity to starting parameters.
- Convergence of the KF iterations.
- Sensitivity to starting values for the covariance matrix of predicted residuals (C_p).

Tests of the Kalman Filter

Helix Fitting in 3D

- Particle's momentum at the target

$$P_x = \frac{cB}{2|K|} \cos \varphi$$

$$P_y = \frac{cB}{2|K|} \sin \varphi$$

$$P_z = \frac{cB}{2|K|} \tan \lambda$$

B: magnetic field
 K: inverse of radius of curvature R
 φ : azimuthal angle
 λ : dip angle
 (parameters at the target)

- Helix equations

$$u = u_0 + \frac{1}{K} (\cos \varphi - \cos \varphi_0)$$

$$v = v_0 + \frac{1}{K} (\sin \varphi - \sin \varphi_0)$$

$$z = z_0 + \frac{1}{K} \tan \lambda (\varphi - \varphi_0)$$

- State vector

$$x_k = \begin{pmatrix} U \\ M \\ \lambda \\ \varphi \end{pmatrix}$$

- Measurement Vector

$$m_k = \begin{pmatrix} U \\ M \end{pmatrix}$$

- Measurement transformation matrix

$$H^{uz} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$H^{vz} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Extrapolation and Transport

• Extrapolate from detector k-1 to detector k

• The Transport matrix

– Calculate the ϕ angle at detector k

$$\varphi_k = \varphi_{k-1} + K \frac{z_k - z_{k-1}}{\tan \lambda}$$

– Calculate the X/Y coordinates

$$u_k = u_{k-1} + \frac{1}{K} (\cos \varphi_k - \cos \varphi_{k-1})$$

$$v_k = v_{k-1} + \frac{1}{K} (\sin \varphi_k - \sin \varphi_{k-1})$$

– Assume that

$$K_k = K_{k-1}$$

$$\tan \lambda_k = \tan \lambda_{k-1}$$

$$F_{k-1} = \begin{pmatrix} \frac{\partial u_k}{\partial u_{k-1}} & \frac{\partial u_k}{\partial v_{k-1}} & \frac{\partial u_k}{\partial K_{k-1}} & \frac{\partial u_k}{\partial \tan \lambda_{k-1}} & \frac{\partial u_k}{\partial \varphi_{k-1}} \\ \frac{\partial v_k}{\partial u_{k-1}} & \frac{\partial v_k}{\partial v_{k-1}} & \frac{\partial v_k}{\partial K_{k-1}} & \frac{\partial v_k}{\partial \tan \lambda_{k-1}} & \frac{\partial v_k}{\partial \varphi_{k-1}} \\ \frac{\partial K_k}{\partial u_{k-1}} & \frac{\partial K_k}{\partial v_{k-1}} & \frac{\partial K_k}{\partial K_{k-1}} & \frac{\partial K_k}{\partial \tan \lambda_{k-1}} & \frac{\partial K_k}{\partial \varphi_{k-1}} \\ \frac{\partial \tan \lambda_k}{\partial u_{k-1}} & \frac{\partial \tan \lambda_k}{\partial v_{k-1}} & \frac{\partial \tan \lambda_k}{\partial K_{k-1}} & \frac{\partial \tan \lambda_k}{\partial \tan \lambda_{k-1}} & \frac{\partial \tan \lambda_k}{\partial \varphi_{k-1}} \\ \frac{\partial \varphi_k}{\partial u_{k-1}} & \frac{\partial \varphi_k}{\partial v_{k-1}} & \frac{\partial \varphi_k}{\partial K_{k-1}} & \frac{\partial \varphi_k}{\partial \tan \lambda_{k-1}} & \frac{\partial \varphi_k}{\partial \varphi_{k-1}} \end{pmatrix}$$

Sensitivity to Starting Parameters & Number of Measurements

(1) Sensitivity to R

- Generated helix parameters:

$$\phi_0 = 45^\circ$$

$$u_0 = +5 \text{ cm}$$

$$v_0 = -5 \text{ cm}$$

$$\lambda = 60^\circ$$

- Fit starting parameters:

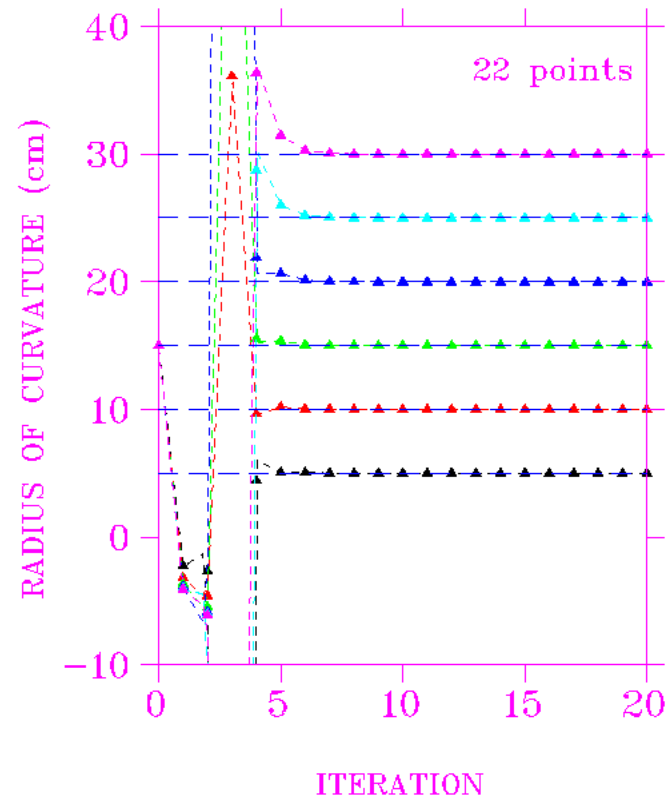
$$\phi_0 = 0^\circ$$

$$u_0 = 0 \text{ cm}$$

$$v_0 = 0 \text{ cm}$$

$$\lambda = 40^\circ$$

$$R = 5 \text{ cm}$$



Sensitivity to Starting Parameters & Convergence Tests

Generated helix parameters:

$$\phi_0 = 45^\circ$$

$$u_0 = +5 \text{ cm}$$

$$v_0 = -5 \text{ cm}$$

$$R = 15 \text{ cm}$$

$$\lambda = 50^\circ$$

Fit starting parameters:

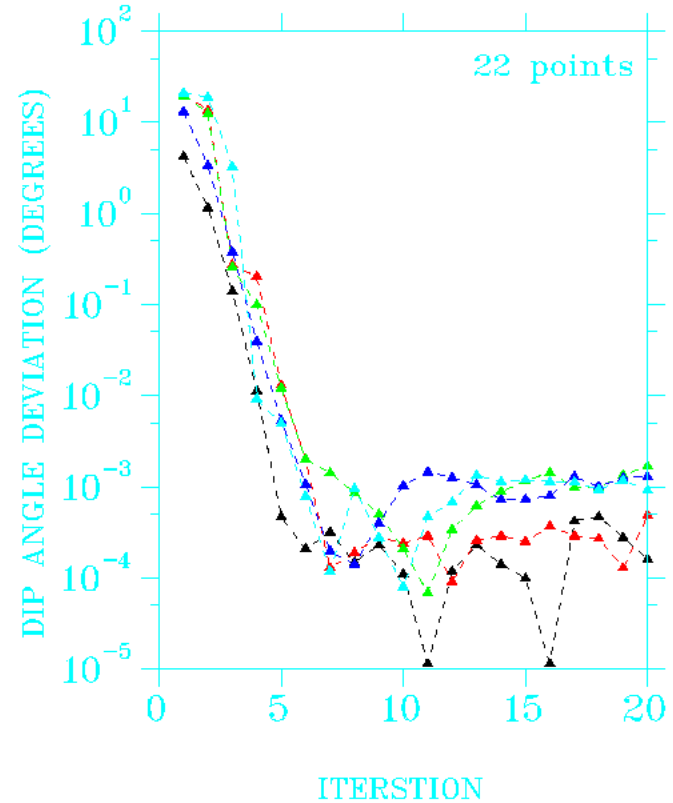
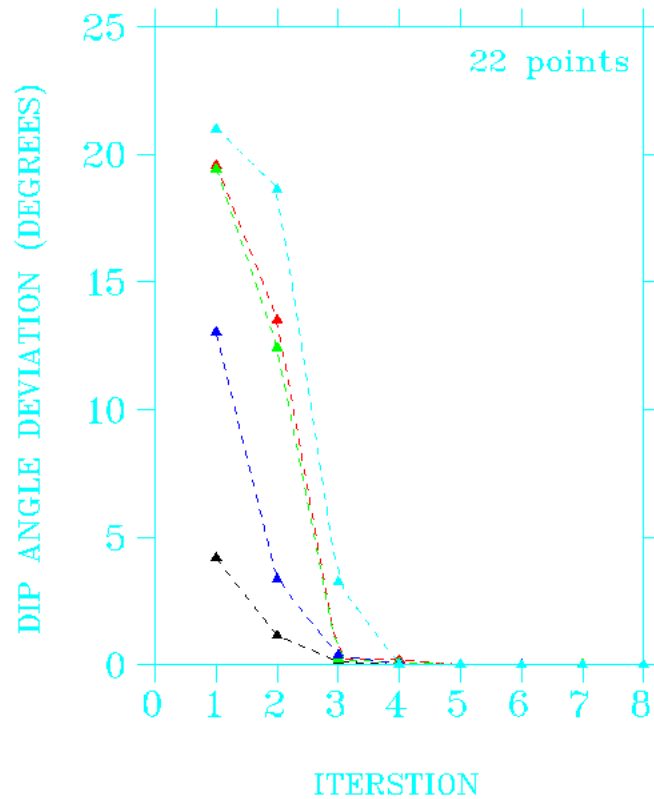
---- 10% off

---- 30% off

---- 50% off

---- 70% off

---- 90% off



Convergence & Sensitivity to Covariance Matrix

Generated helix parameters:

$$\phi_0 = 45^\circ$$

$$u_0 = +5 \text{ cm}$$

$$v_0 = -5 \text{ cm}$$

$$\lambda = 60^\circ$$

Fit starting parameters:

$$\phi_0 = 0^\circ$$

$$u_0 = 0 \text{ cm}$$

$$v_0 = 0 \text{ cm}$$

$$R = 15 \text{ cm}$$

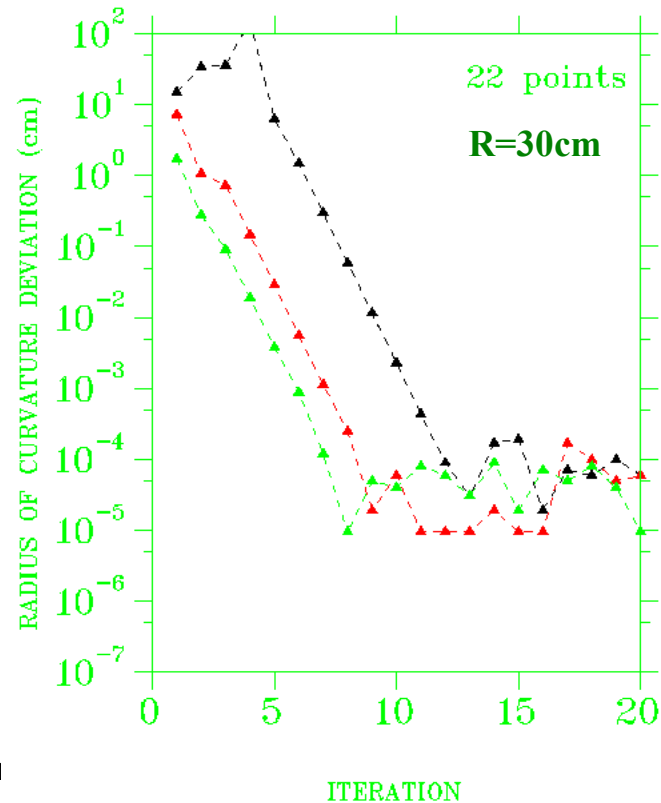
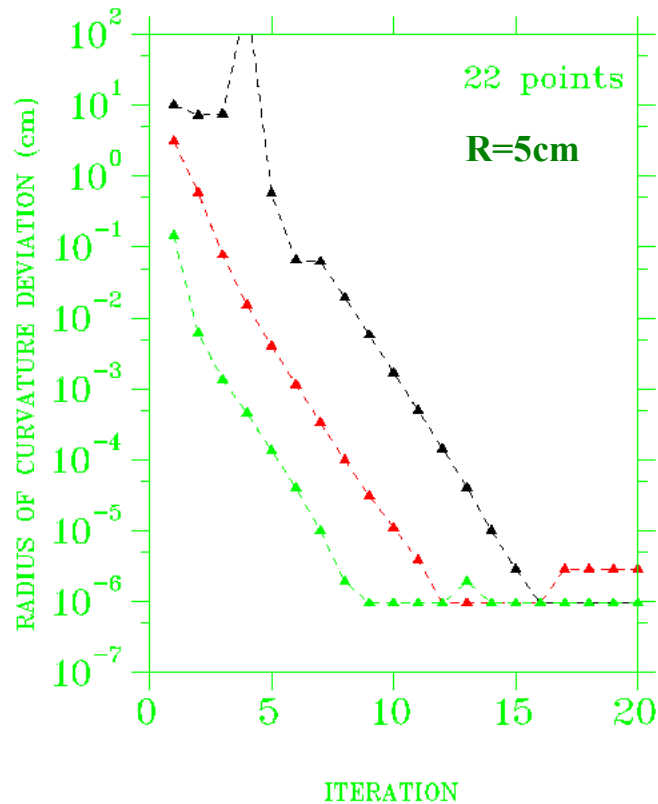
$$\lambda = 40^\circ$$

Fit starting parameters:

$$\text{---} C_p = 0.1$$

$$\text{---} C_p = 0.001$$

$$\text{---} C_p = 0.00001$$



Conclusions

- Helix fitting in 3-D.
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- Are there any failure modes?
- Sensitivity to starting parameters.
- Convergence of the KF iterations.
- Sensitivity to starting values for the covariance matrix of predicted residuals (C_p).

Works fine! Verifies correct formulation, derivatives and code.

Works fine when iterated.

None intrinsic to KF (C_p sensitive).

Not too sensitive (might change with correct choice of C_p).

Converges over a range of about 6-8 iterations (C_p dependent).

Fairly sensitive.